AX-EM-4DA Analog Output Module User Manual

AX-EM-4DA Analog Output Module User Manual

Thanks for choosing AX series programmable controller (programmable controller for short).

AX-EM-4DA analog output module (AO module for short) is a 16-bit resolution, 4-channel analog output module that works with the main module of the programmable controller. Each channel of the AO module supports voltage and current output.

The manual mainly describes the specifications, features, wiring, and use methods of the module. To ensure that you use the product safety and properly and bring it into full play, read the manual carefully before the installing. For details about the user program development environments and user program design methods, see AX Series Programmable Controller Hardware User Manual and AX Series Programmable Controller Software User Manual that we issue.

The manual is subject to change without prior notice. Please visit www.invt.com to download the latest manual version.

1 Safety precautions

1.1 Warning signs

| Sign | Name | Description | Abbreviation |
|----------|---------|---|--------------|
| A Danger | Danger | Serious physical injury or even death may occur if related requirements are not followed. | A |
| Marning | Warning | Physical injury or device damage may occur if related requirements are not followed. | \triangle |

1.2 Delivery and installation

- Only trained and qualified electricians are allowed to perform installation, wiring, maintenance, and inspection for AX series programmable controller.
- Do not install AX series programmable controller on inflammables. In addition, prevent AX series programmable controller from contacting or adhering to inflammables.



- Install AX series programmable controller in a lockable control cabinet of at least IP20, which prevents the personnel without electrical equipment related knowledge from touching by mistake, since the mistake may result in device damage or electric shock. Only personnel who have received related electrical knowledge and equipment operation training can operate the control cabinet.
- Do not run AX series programmable controller if it is damaged or incomplete.
- Do not contact AX series programmable controller with damp objects or body parts. Otherwise, electric shock may result.

1.3 Wiring

- Only trained and qualified electricians are allowed to perform installation, wiring, maintenance, and inspection for AX series programmable controller.
- Fully understand the interface types, specifications, and related requirements before wiring. Otherwise, incorrect wiring will cause abnormal running.
- Cut off all power supplies connected to AX series programmable controller before performing wiring.
- Before power-on for running, ensure that the module terminal cover is properly installed in place after the installation and wiring are completed. This prevents the live terminal from being touched. Otherwise, physical injury, device fault or misoperation may result.
- Install proper protection components or devices for external power supply input to AX series programmable controller. This prevents the controller from being damaged due to external power supply faults, overvoltage, overcurrent, or other exceptions.

1.4 Commission and running



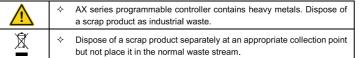
- Before power-on for running, ensure that the working environment of AX series programmable controller meets the requirements, the wiring is correct, the input power specifications meet the requirements, and the respective protection circuit has been designed to protect the controller so that the controller can run safely even if an external device fault occurs.
- For modules or terminals requiring external power supply, configure external safety devices such as fuses or circuit breakers to avoid damage caused due to external power supply or device fault.

1.5 Maintenance and component replacement



- Only trained and qualified electricians are allowed to perform maintenance, inspection, and component replacement for AX series programmable controller.
 Cut off all power supplies connected to AX series programmable
- controller before wiring AX series programmable controller terminals.
 During maintenance and component replacement, take measures to prevent conductive materials such as screws and cables from falling into the internal of AX series programmable controller.

1.6 Disposal



2 Product introduction

2.1 Model and nameplate

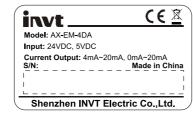


Figure 2.1 Product nameplate

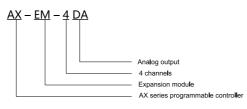


Figure 2.2 Product model

2.2 Product function

As an expansion module of the programmable controller, the AO module supports 4 channels of voltage and current output. The voltage output ranges are bipolar $\pm 5V$ and $\pm 10V$ and unipolar $\pm 5V$ and $\pm 10V$, and the range of the load that can be driven is $1k\Omega-1M\Omega$. The output range of current output mode is 4mA-20mA and 0mA-20mA, and the range of the load that can be driven is $0-1k\Omega$.

2.3 Structural dimensions

The structural dimensions (unit: mm) of the module are shown in the following figure

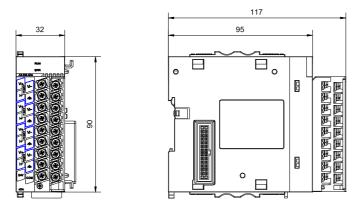


Figure 2.3 Mounting dimensions

3 Interfaces

3.1 Interface appearance

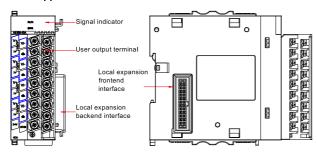


Figure 3.1 Interface distribution

| Interface | Function |
|------------------------------------|--|
| Signal indicator | RUN indicator: it is on when the operation is normal and off when the operation is faulty. ERR indicator: it is off when the operation is normal and on when the operation is faulty. |
| User output terminal | 4 outputs (support voltage/current output) |
| Local expansion frontend interface | Connects to the frontend module, disallowing hot swapping |

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3.2 Terminal definition

| Terminal No. | Channel | Terminal symbol | Туре | Function |
|-----------------|---------|--------------------|--------------|----------------------------------|
| 1 | | V+ | Output | Channel 0 voltage output |
| 2 | CH0 | VI- | Output | Channel 0 voltage/current output |
| 3 | | + | Output | Channel 0 current output |
| 4 | | \$ | 1 | Shield ground |
| 5 | | V+ | Output | Channel 1 voltage output |
| 6 | CH1 | VI- | Output | Channel 1 voltage/current output |
| 7 | | + | Output | Channel 1 current output |
| 8 | | | 1 | Shield ground |
| 9 | | V+ | Output | Channel 2 voltage output |
| 10 | CH2 | VI- | Output | Channel 2 voltage/current output |
| 11 | | + | Output | Channel 2 current output |
| 12 | | | 1 | Shield ground |
| 13 | | V+ | Output | Channel 3 voltage output |
| 14 | CH3 | VI- | Output | Channel 3 voltage/current output |
| 15 | | + | Output | Channel 3 current output |
| 16 | | | 1 | Shield ground |
| 17 | , | 24V | Power supply | 24V power supply |
| 18 | / | СОМ | Power ground | Power ground |

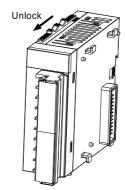
4 Installation and wiring

Using modular design, the programmable controller is easy to install and maintain. As for the AO module, the main connection objects are the CPU module, EtherCAT module, and expansion modules.

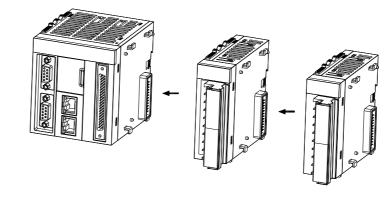
The modules are connected by using the module-provided connection interfaces and snap-fits.

4.1 Installation procedure

Step 1 Slide the snap-fit on the AO module in the direction shown in the following figure.



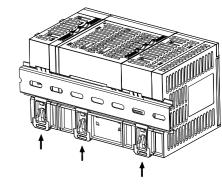
Step 2 Align the AO module with the CPU module connector for interlocking.



Step 3 Slide the snap-fit in the direction shown in the following figure to connect and lock the two modules.

Lock

Step 4 As for standard DIN rail installation, hook the respective module into the standard installation rail until the snap-fit clicks into place.



4.2 Wiring instruction

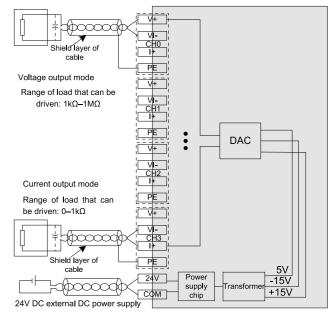


Figure 4.1 Wiring diagram of user terminals

Notes:

- Adopt two-core shielded twisted pairs as the power cable.
- If there is noise or ripple in the external wiring, you can connect a capacitor with a capacitance of 0.1mF to 0.47mF and withstanding voltage of 25V between the V+/I terminal and the VI- terminal.
- The AO module needs to be installed on a properly-grounded metal bracket, and the metal dome at the module bottom must be in good contact with the bracket.
- Do not bind the output cable of the module together with AC cable, main circuit cable, or high
 voltage cable. Otherwise, the binding can increase the impact of noise, surge and induction.
 When using shielded cables, use single-point grounding for the shield layer.

5 Technical parameters

5.1 Power supply

| Item | Specification |
|-------------------------------|-----------------------|
| External power supply | 24V DC (-15%-+20%) |
| Internal 5V power consumption | 100mA (typical value) |

3

5.2 Performance parameters

| Item | Specification | |
|----------------------------------|--|--|
| Voltage output range | Bipolarity ±5V, ±10V, unipolarity +5V, +10V | |
| Current output range | 4mA–20mA, 0mA–20mA | |
| Voltage output load | 1kΩ–1MΩ | |
| Current output load | 0Ω–1kΩ | |
| Precision (room temperature 25℃) | Voltage ±0.1%, current ±0.1% (full scale) | |
| Resolution | 16 bits | |
| Conversion time | 1ms/channel | |
| Output short circuit protection | Enable | |
| System program upgrade mode | Serial upgrade | |
| Isolation method | Output terminals isolated from the power supply terminals, and no isolation between channels | |

6 Application instance

For instance, channel 0 of the AO module outputs voltage of 10V. The AX70-C-1608P module is used as the main control module, and the high-speed I/O interface board is connected to the AO

Step 1 Create a new project on the CODESYS upper PC, add the corresponding CPU device, and add the device description file (IoDrv4DA) corresponding to the AO module in the project, as shown in the following figure.

| String for a fulltext search | Vendor | <all vendors=""></all> | | , |
|----------------------------------|-----------------------|------------------------|---------------|--------|
| Name | Vendo | or | Version | De: ^ |
| □ Miscellaneous | | | | |
| IoDrv4AD | INVT | | 1.1.0.0 | IoDr |
| - ☐ IoDrv4DA | INVT | | 1.1.0.0 | IoDr |
| ■ IoDrvDI16 | INVT | | 1.1.0.0 | IoDr |
| IoDrvDO16 | INVT | | 1.1.0.0 | IoDr |
| IoDrvHighSpeed | INVT | | 1.0.0.0 | For |
| IoDryTemperature | INVT | | 1.1.0.0 | IoDr _ |
| · | 1 | | | Þ |
| Group by category Display all ve | rsions (for experts o | only) 🔲 Display outda | ated versions | |
| Name: IoDrv4DA | | | | |
| Vendor: INVT | | | | |
| Categories: | | | | D |
| Version: 1.1.0.0 | | | | |
| Order Number: | | | - | h |

Step 2 Double-click IoDrv4DA in the Device bar, you can see the configuration variables of the parameters related to each channel on the Internal I/O Mapping interface, and you can configure it as needed. Note that in CODESYS upper PC, the number and order of the added I/O expansion modules must be consistent with the actual configuration of the hardware. In this application, the CODESYS upper PC interface is shown in the following

| = 0 1 Device [connected] (INVT AX70) | PCI-Bus IEC Objects | Find | | Filter Show all | | | Add F |
|--------------------------------------|----------------------|----------|---------|-------------------|---------|------|---------------------------|
| PLC Logic | Internal Parameters | Variable | Mapping | Channel | Address | Туре | Current Value |
| = O Application [run] | | * * | | Configuration_CH0 | %QW22 | INT | |
| Library Manager | Internal I/O Mapping | - 0 | | Data_CH0 | %QW23 | INT | |
| PLC_PRG (PRG) | | ** | | Data_Default0 | %QW24 | INT | |
| Task Configuration | Status | * * | | Configuration_CH1 | %QW25 | INT | |
| = 6 🕸 MainTask | Information | | | Data_CH1 | %QW26 | INT | |
| ● PLC_PRG | | - 0 | | Data_Default1 | %QW27 | INT | |
| → S HIGH_PULSE_IO | | 8.0 | | Configuration_CH2 | %QW28 | INT | |
| G IoDrv4DA (IoDrv4DA) | | - 0 | | Data_CH2 | %QW29 | INT | |
| SoftMotion General Axis Pool | | | | Data_Default2 | %QW30 | INT | |
| | | H-10 | | Configuration_CH3 | %QW31 | INT | |
| | | - ** | | Data_CH3 | %QW32 | INT | |
| | | - "0 | | Data_Default3 | %QW33 | INT | |
| | | *9 | | Version_FPGA | %IB3 | BYTE | |
| | | - 46 | | Version_MCU | %IB4 | BYTE | |

The variables of channel 0 are described as follows.

| | Parameter | | Value | Valid bit | Variable name |
|-----------------------|-------------------------|----------|-------|-----------|-------------------|
| | Channel | Enable | 1 | [0] | CN Frahla |
| Configuration | enabling | Disable | 0 | [0] | CN_Enable |
| items of channel 0 | Disconnection detection | Reserved | | [1] | CN_Diagnosis |
| | Conversion | 0V~5V | 000 | [4: 2] | Conversion_Mode_B |

| | Parameter | | Value | Valid bit | Variable name |
|--|--------------------------------|---------------------|-------|-----------|-------------------------------------|
| | mode | 0V~10V | 001 | | t0 |
| | | -5V~5V | 010 | | Conversion_Mode_Bi |
| | | -10V~10V | 011 | | t1 |
| | | 4mA~20mA | 100 | | Conversion_Mode_Bi |
| | | 0mA~20mA | 101 | | t2 |
| | | Output zeroing | 00 | | |
| | Output state after stopping | Output retention | 01 | [6: 5] | Output_State_Bit0 Output_State_Bit1 |
| | | Preset output value | 10 | | |
| | Reser | ved | | [15: 7] | Reserved |
| ASCII code value of channel 0 | Data | | | [15: 0] | Data_CH0 |
| Preset output value of channel 0 | Preset out | out value | | [15: 0] | Data_Default0 |

The relationship between mapping and actual analog input values is shown as follows.

| Туре | Rated input range | Rated digital value |
|----------------|-------------------|---------------------|
| | -10V-10V | -10000-+10000 |
| Analog voltage | 0V-10V | 0-10000 |
| output | -5V-+5V | - 5000-+5000 |
| | 0V-5V | 0-5000 |
| Analog current | 4mA-20mA | 4000–20000 |
| output | 0mA-20mA | 0-20000 |

The AO module fault codes are listed in the following table.

| Fault code | Fault type | Solution |
|------------|--|--|
| 16#b0 | The current output of channel 0 is disconnected. | Check whether the current channel is disconnected. If yes, restore the connection. |
| 16#b1 | The voltage output of channel 0 is short circuited. | Check whether the voltage channel is disconnected. If yes, restore the connection. |
| 16#b2 | The current output of channel 1 is disconnected. | Check whether the current channel is disconnected. If yes, restore the connection. |
| 16#b3 | The voltage output of channel 1 is short circuited. | Check whether the voltage channel is disconnected. If yes, restore the connection. |
| 16#b4 | The current output of channel 2 is disconnected. | Check whether the current channel is disconnected. If yes, restore the connection. |
| 16#b5 | The voltage output of channel 2 is short circuited. | Check whether the voltage channel is disconnected. If yes, restore the connection. |
| 16#b6 | The current output of channel 3 is disconnected. | Check whether the current channel is disconnected. If yes, restore the connection. |
| 16#b7 | The voltage output of channel 3 is short circuited. | Check whether the voltage channel is disconnected. If yes, restore the connection. |
| 16#b8 | The 24V power board of the output module is powered off. | Check whether the 24 power supply is proper and whether reverse wiring happens. |

Step 3 Perform programming by using ST programming language, map the variables defined in the program to the variables relating to channel 0 of the AX-EM-4DA module, and complete the variable mapping. Configure the Configuration_CH0 variable of channel 0, based on the description of each variable of channel 0, use channel 0, select the voltage range -10V-10V, and 13 (000000000001101) is assigned. The digital value corresponding to -10V–10V is -10000–10000, so 10000 is assigned to Data_CH0. After the hardware device is powered on, log in to the device, and run the program as shown in the following figure. Measured by relevant instruments, channel 0 outputs $\pm 10V$ voltage, as shown in the following figure.

| NVT 深圳市英區獨电气股份有限公司 SHENZHEN INVT ELECTRIC CO., LTD. | AX-EM-4DA Analog Output Module User Manual | | |
|--|--|--|--|
| Devices Device (DIVT AX70) Device (DIVT AX70 | PIC_PRG X Device 100rv4DA 1 FROGRAM FLC_FRG 2 VAR 4 Con_CBO, Data_CBO, Data_Default0:INT; 5 Con_CBI, Data_CBI, Data_Default1:INT; 6 Con_CBI, Data_CBI, Data_Default2:INT; 7 Con_CBI, Data_CBI, Data_Default3:INT; 8 END_VAR | | |
| | H 1 //DA 2 Con_CHO:=13:Deta_CHO:=100000; 3 //Con_CHI.Data_CHI.Data_Default::INT; 4 //Con_CHI.Data_CHI.Data_Default2:INT; 5 //Con_CHI.Data_CHI.Data_Default3:INT; | | |

Step 4 After the program is compiled successfully, log in to the device, and run the program.



7 Pre-startup check and preventive maintenance

7.1 Pre-startup check

If you have completed the wiring, ensure the following aspects before starting the module to work:

- The module output cables meet requirements.
- The expansion interfaces at all levels are reliably connected.
- The application programs use the correct operation methods and parameter settings.
- The RUN indicator is on.

7.2 Preventive maintenance

Perform preventive maintenance as follows:

- Clean the programmable controller regularly, and ensure good ventilation and heat dissipation conditions for the controller.
- Formulate maintenance instructions and regularly test the controller.
- Regularly check the wiring and terminals to ensure that they are securely fastened.

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