AX-EM-4AD Analog Input Module User Manual

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Thanks for choosing AX series programmable controller (programmable controller for short)

AX-EM-4AD analog input module (AI module for short) is a 24-bit resolution, 4-channel analog input module that works with the main module of the programmable controller. Each channel of the AI module supports voltage and current input.

The manual mainly describes the specifications, features, wiring, and use methods of the Al module of AX series programmable controller. To ensure that you use the product safety and properly and bring it into full play, read the manual carefully before the installing. For details about the user program development environments and user program design methods, see AX Series Programmable Controller Hardware User Manual and AX Series Programmable Controller Software User Manual that we issue.

The manual is subject to change without prior notice. Please visit www.invt.com to download the latest manual version.

1 Safety precautions

1.1 Warning signs

Sign	n	Name	Description	Abbreviation
♣)anger	Danger	Serious physical injury or even death may occur if related requirements are not followed.	A
<u></u> ∧	/arning	Warning	Physical injury or device damage may occur if related requirements are not followed.	\wedge

1.2 Delivery and installation

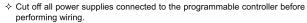
- Only trained and qualified electricians are allowed to install, wire, maintain, and inspect the programmable controller.
- Do not install the programmable controller on inflammables. In addition, prevent the programmable controller from contacting or adhering to inflammables.



- Install the programmable controller in a lockable control cabinet of at least IP20, which prevents the personnel without electrical equipment related knowledge from touching by mistake, since the mistake may result in device damage or electric shock. Only personnel who have received related electrical knowledge and equipment operation training can operate the control cabinet.
- Do not run the programmable controller if it is damaged or incomplete.
 Do not contact the programmable controller with damp objects or body
- parts. Otherwise, electric shock may result.

1.3 Wiring

- Only trained and qualified electricians are allowed to install, wire, maintain, and inspect the programmable controller.
- Fully understand the interface types, specifications, and related requirements before wiring. Otherwise, incorrect wiring will cause abnormal running.





- Before power-on for running, ensure that the module terminal cover is properly installed in place after the installation and wiring are completed. This prevents the live terminal from being touched. Otherwise, physical injury, device fault or misoperation may result.
- Install proper protection components or devices when using external power supplies for the programmable controller. This prevents the controller from being damaged due to external power supply faults, overvoltage, overcurrent, or other exceptions.

1.4 Commissioning and running



- Before power-on for running, ensure that the working environment of the programmable controller meets the requirements, the wiring is correct, the input power specifications meet the requirements, and a protection circuit has been designed to protect the controller so that the controller can run safely even if an external device fault occurs.
- For modules or terminals requiring external power supply, configure external safety devices such as fuses or circuit breakers to prevent damage caused due to external power supply or device faults.

1.5 Maintenance and component replacement



- Only trained and qualified electricians are allowed to perform maintenance, inspection, and component replacement for the programmable controller.
 Cut off all power supplies connected to the programmable controller before
- wiring programmable controller terminals.

 During maintenance and component replacement, take measures to

prevent conductive materials such as screws and cables from falling into the

internal of the programmable controller. 1.6 Disposal



The programmable controller contains heavy metals. Dispose of a scrap product as industrial waste.



Dispose of a scrap product separately at an appropriate collection point but not place it in the normal waste stream.

1

2 Product introduction

2.1 Model and nameplate



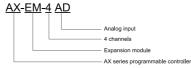


Figure 2.1 Product nameplate

Figure 2.2 Product model

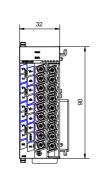
2.2 Function overview

The AI module is an expansion module of the programmable controller main module and belongs to special function modules.

The AI module has 4 analog signal input channels, with 24-bit resolutions. At input terminals, you can perform current or voltage input, and select different current ranges, including -20mA-+20mA, 0mA-20mA, and 4mA-20mA, or voltage ranges, including 0V-5V, 0V-10V, -5V-+5V, and -10V-+10V, with the measuring result accurate to 0.001.

2.3 Structural dimensions

The structural dimensions (unit: mm) of the AI module are shown in the following figure.



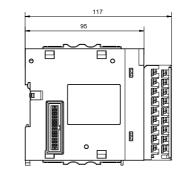


Figure 2.3 Structural dimensions

3 Interfaces

3.1 Interface distribution

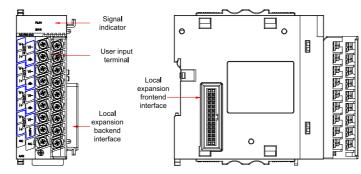


Figure 3.1 Interface distribution

Interface	Function
Signal indicator	RUN: running status indicator. It is on when the running is normal, and it is off when the running is abnormal. ERR: error status indicator. It is on when the running is abnormal, and it is off when the running is normal.
User output terminal	4 inputs
Local expansion frontend interface	Connects to frontend modules. Disallows hot swapping.
Local expansion backend interface	Connects to backend modules. Disallows hot swapping.

3.2 Terminals

Terminal No.	Channel	Terminal symbol	Туре	Function
1		V+	Input	Voltage input of channel 0
2		VI-	Input	Voltage/current input of channel 0
3	CH0	+	Input	Current input of channel 0
4		\leftarrow	1	Shield ground (internally connected to the housing ground)
5		V+	Input	Voltage input of channel 1
6		VI-	Input	Voltage/current input of channel 1
7	CH1	l+	Input	Current input of channel 1
8		4	1	Shield ground (internally connected to the housing ground)
9		V+	Input	Voltage input of channel 2
10	CH2	VI-	Input	Voltage/current input of channel 2
11		+	Input	Current input of channel 2

Termin Terminal Channel Type Function symbol Shield ground (internally 12 \triangle connected to the housing ground) V+ 13 Input Voltage input of channel 3 14 VI-Input Voltage/current input of channel 3 15 1+ Input Current input of channel 3 CH3 Analog 16 AGND Analog signal ground signal ground 17 NC No connection 18 NC No connection

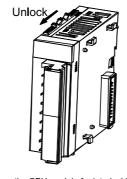
4 Installation and wiring

Using modular design, the programmable controller is easy to install and maintain. As for the Al module, the main connection objects are the CPU module, EtherCAT module, and expansion modules.

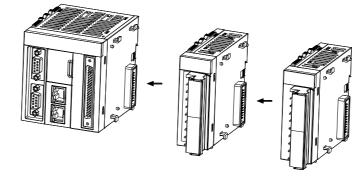
The modules are connected by using the module-provided connection interfaces and snap-fits.

4.1 Installation procedure

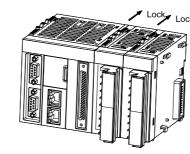
Step 1 Slide the snap-fit on the AI module in the direction shown in following figure.



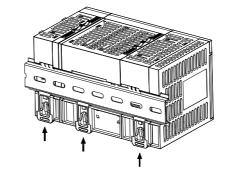
Step 2 Align with the connector on the CPU module for interlocking.



Step 3 Slide the snap-fit in the direction shown in the following figure to connect and lock the two modules.



Step 4 As for standard DIN rail installation, hook the respective module into the standard installation rail until the snap-fit clicks into place.



4.2 Wiring

The user terminal wiring is shown in the following figure.

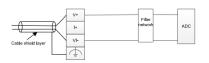


Figure 4.1 Wiring for voltage input

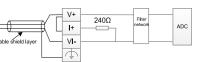


Figure 4.2 Wiring for current input

Note:

- For voltage input, use V+ and VI- for input, as shown in figure 4.1, and ensure the voltage input is within the range.
- For current input, connect V+ to I+ in short circuit mode, as shown in figure 4.2, and ensure the current input is within the range.
- The Al module needs to be installed on a properly-grounded metal bracket, and the metal dome at the module bottom is in good contact with the bracket.
- Do not bind the analog input cable together with the AC cable, main circuit cable, or high-voltage cable. Otherwise, the binding can increase noise, surge, and induction impact.
 When using shielded cables, use single-point grounding for the shield layer.

5 Technical parameters

5.1 Power parameters

Parameter	Specifications	
Supply voltage	Internal power supply, 5VDC (-10%–10%)	
Consumption of internal 5V power supply	138mA (typical value)	

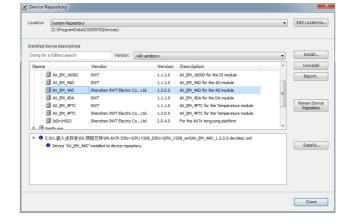
5.2 Performance parameters

Parameter	Specifications
Input channels	4
Voltage input impedance	2.4ΜΩ
Current sampling impedance	240Ω
Voltage input range	Unipolar: 0V–5V, 0V–10V; Bipolar: -5V–+5V, -10V–+10V
Current input range	-20mA-+20mA, 0mA-20mA, 4mA-20mA
Resolution	24 bits
Accuracy (at normal temperature 25°C)	Voltage: ±0.1%; Current: ±0.1% (full measuring range)
Limiting voltage	±12V
Limiting current	±24mA
Max. common-mode voltage between channels	30VDC
Insulation mode	I/O terminals insulated from the power supply; No insulation between channels
System program upgrade method	Using the serial port

6 Application instance

The following assumes that channel 0 of the AI module collects voltage samples and assigns the sampling values to the corresponding variables; AX70-C-1608P is the main module of the programmable controller, and the high-speed I/O interface board connects to the AI module (only one).

Step 1 Start CODESYS, choose **File > New Project** to create a new project. Install the device description file (AX_EM_4AD_1.x.x.x.devdesc.xml) corresponding to the AX-EM-4AD module in the project, as shown in the following figure.



4

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Step 2 Right click on the CPU module to add a device and select the AX-EM-4AD device. Double click AX_EM_4AD in the **Devices** bar after installation. Set parameters on the **Internal I/O Mapping** interface. Note that the quantity and sequence of the I/O expansion modules added in the CODESYS interface must be the same as the actual hardware configuration. See the following figure.

Devices						
■ ASIO test ■ B INVT_AX7X (INVT AX7X)	PCI-Bus IEC Objects	Find		Filter Show all		
□ □ PLC Logic	Internal Parameters	Variable	Mapping	Channel	Address	Туре
	Incinal Formittees	#-T#		CH0	%QW22	UDNT
→ high_pulse_to	Internal I/O Mapping	B- 6		CH1	%QW23	UBNT
AX_EM_4AD (AX_EM_4AD)		#- T#		CH2	%QW24	UINT
SoftMotion General Axis Pool	Status	⊕-**		CH3	%QW25	UINT
	Information	"#		FP	%QW26	UENT
		-**		FP0	%Q854	USIN
		***		FP1	%Q855	USIN
		-**		FP2	%Q856	USINT
		*o		FP3	%Q857	USINT
		-16		INO	%IW2	INT
		*b		IN1	%IW3	INT
		-19		IN2	%IW4	INT
		*b		IN3	%IW5	INT
		-19		Version_FPGA	%IW6	INT
		- Np		Version_MCU	%EW7	INT

Step 3 Use the ST programming language to write a program, and map the variables defined in the program to channel 0 of the AI module. Set CH0 and FP0 variables of channel 0. According to the variable description of channel 0, select the filter sinc3, and set FP to 1 (2#0000 0000 0000 0001). Select the voltage measuring range -10-+10V and set CH0 to 13 (2#0000 0000 0000 1101). Take the average of 10 sampling values for filtering, and set FP0 to 10. After the hardware is turned on, log in, and download the project for running. See the following figure. Input 5.2V voltage to channel 0, you can read 5241 from channel IN0 on the CODESYS interface. According to the mapping table, you can obtain the information that 5.241V is input to channel 0.

HSIO test	PCI-Bus IEC Objects	Find		Filter Show all			
⊕-Bil PLC Logic	Internal Parameters	Variable	Mappin	ng Channel	Address	Type	Current Value
* O Application [run]	Internal Parameters	# - * Application.ad.CH0	~	CH0	N-QW-2	UINT	13
- 5 % HIGH_PULSE_10	Internal I/O Mapping	8-**		CH1	%QW3	UINT	
G AX_EM_4AD (AX_EM_4AD)		*-**		CH2	%QW4	UBNT	
- 🤥 🦫 SoftMotion General Axis Pool	Status	8-10		CH3	%QW5	UINT	
	Information	- * Application.ad.FP		FP	9LQW6	UBNT	1
		- * Application.ad.FP0	7	FP0	94Q814	USINT	10
		- **		FP1	%Q815	USINT	
		- **		FP2	%Q816	USINT	
		- **		FP3	%Q817	USINT	
		- * Application.ad.INO	**	INO	44W2	INT	5241
		- **		IN1	%ZW3	INT	
				IN2	%ZW4	INT	
		- *p		IN3	%ZW5	INT	
		- * Application.ad.Version_FPGA		Version_FPGA	NZW6	INT	65
		Application.ad.Version_MCU	70	Version_MCU	46W7	INT	66

Step 4 Read FPGA version 1.01 (65 is converted to octal system) and MCU version 1.02 (66 to is converted to octal system) during running.

Table 6.1 Variables of channel 0

Table 0.1 Variables of Charlie 0							
Parameter				Valid bits	Variable name	Variable type	
	sinc5-	00					
Filter selection	sinc5+sinc1+e	enhance 50/60	01	[1:0]	FP	UINT	
Filler Selection	sir	10	[1.0]	FF	Olivi		
	Rese	erved					
Filtering parameter configuration	FP0			[7:0]	FP0	USINT	
	Channel	Enable	1	101	ON Frable		
	enabling	Disable	0	[0] CN_Enable			
	Disconnection	Enable	1	[1] BK			
	detection	Disable	0	[1]	BK		
	Conversion mode	0V-5V	000	[4:2]	CM_Bit0 CM_Bit1 CM_Bit2		
		0V-10V	001				
		-5V - 5V	010				
		-10V – 10V	011				
Configuration		-20mA-20mA	100			UINT	
items of channel 0		0mA-20mA	101			Ollvi	
		4mA-20mA	110				
	Limit	Enable	1	[5]	OVR		
	exceeding flag	Disable	0	ادا	OVIC		
	Measuring range	Enable	1	[6]	ORD		
	detection enabling bit	Disable	0				
	Rese	erved		[15:7]	Reserved		
Data item of channel 0	Data			[15:0]	IN0	INT	

Table 6.2 Mapping between actual analog input values and rated values

Туре	Rated range	Digital
	-10V – +10V	-10000 – +10000
Analog voltage	0V-10V	0-10000
input	-5V — +5V	- 5000 – +5000
	0V-5V	0–5000
A I	-20mA – +20mA	-20000 – +20000
Analog current	0mA-20mA	0–20000
input	4mA–20mA	4000–20000

5

Table 6.3 Analog input module fault codes

	Table 0.07 Waley Input Modele laut codes					
Fault code	Fault type	Solution				
16#A0	Channel 0 disconnected.	Check whether the connection is proper.				
16#A1	Channel 0 is out of the range (that is, the voltage is out of the range -25V - +25V, or the current is out of the range -104mA - +104mA).	Check whether the input voltage or current value is out of the range.				
16#A2	Channel 0 exceeds the upper limit of the allowed range (that is, the input value is higher than the set upper limit).	Decrease the input voltage or current value, or select a wider range.				
16#A3	Channel 0 does not reach the lower limit of the allowed range (that is, the input value is lower than the set lower limit).	Increase the input voltage or current value, or select a wider range.				
16#A4	Channel 1 disconnected.	Check whether the connection is proper.				
16#A5	Channel 1 is out of the range (that is, the voltage is out of the range -25V = +25V, or the current is out of the range -104mA = +104mA).	Check whether the input voltage or current value is out of the range.				
16#A6	Channel 1 exceeds the upper limit of the allowed range (that is, the input value is higher than the set upper limit).	Decrease the input voltage or current value, or select a wider range.				
16#A7	Channel 1 does not reach the lower limit of the allowed range (that is, the input value is lower than the set lower limit).	Increase the input voltage or current value, or select a wider range.				
16#A8	Channel 2 disconnected.	Check whether the connection is proper.				
16#A9	Channel 2 is out of the range (that is, the voltage is out of the range -25V = +25V, or the current is out of the range -104mA = +104mA).	Check whether the input voltage or current value is out of the range.				
16#AA	Channel 2 exceeds the upper limit of the allowed range (that is, the input value is higher than the set upper limit).	Decrease the input voltage or current value, or select a wider range.				
16#Ab	Channel 2 does not reach the lower limit of the allowed range (that is, the input value is lower than the set lower limit).	Increase the input voltage or current value, or select a wider range.				
16#AC	Channel 3 disconnected.	Check whether the connection is proper.				
16#Ad	Channel 3 is out of the range (that is, the voltage is out of the range -25V - +25V, or the current is out of the range -104mA - +104mA).	Check whether the input voltage or current value is out of the range.				
16#AE	Channel 3 exceeds the upper limit of the allowed range (that is, the input value is higher than the set upper limit).	Decrease the input voltage or current value, or select a wider range.				
16#AF	Channel 3 does not reach the lower limit of the allowed range (that is, the input value is lower than the set lower limit).	Increase the input voltage or current value, or select a wider range.				

7 Pre-startup check and preventive maintenance

7.1 Pre-startup check

If you have completed the wiring, ensure the following before starting the module to work:

- The module input cables meet requirements.
- The expansion interfaces at any levels are reliably connected.
- The application programs use the correct operation methods and parameter settings.
- The RUN indicator is on.

7.2 Preventive maintenance

Perform preventive maintenance as follows:

- Clean the programmable controller regularly, prevent foreign matters falling into the controller, and ensure good ventilation and heat dissipation conditions for the controller.
- Formulate maintenance instructions and regularly test the controller.
- Regularly check the wiring and terminals to ensure that they are securely fastened.

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